

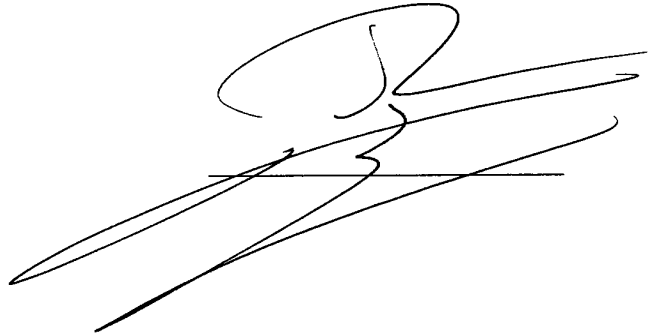
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For : MMT

VERIFICATION OF TRANSLATION

Thierry SCWHARTZ, residing at Paris declares :

- (1) That he knows well both French and English languages ;
- (2) That he translated the above-identified Application from French ;
- (3) That the attached English translation is a true and correct translation of the above identified application to the best of his knowledge and belief ; and
- (4) That all statement made of his own knowledge are true and that all statements made of information and belief re believed to be true, and further that these statements are made with the knowledge that wilful false statements and the like are punishable by fine or imprisonment, or both, under 18 U.S.C. §1001, and that such false statements may jeopardize the validity of the Application or any Patent issuing thereon.

Date : January 4th, 2008

A handwritten signature in black ink, consisting of a large, stylized 'T' followed by a series of horizontal and diagonal strokes, likely representing the name 'Thierry SCWHARTZ'.

ANGULAR POSITION MAGNETIC SENSOR DEVICE

The present invention relates to an angular-position magnetic-sensor device. It is applicable in particular but not exclusively to motorized butterfly valves (ETC), which require a very stable signal at the beginning of travel and a fairly large travel (larger than 90°) with excellent linearity.

In general, contactless systems comprise substantially devices made from angular-position magnetic sensors. In all such devices, the measured signal must be as linear as possible according to angular position.

In order to make both the invention and the angular-position magnetic-sensor devices more comprehensible, it is important to understand the "zero gauss" concept.

The position delivering a signal equal to zero gauss corresponds to the point of high stability. In fact, the variation of induction is measured by means of an intelligent and programmable Hall-effect sensor of ASIC type. This sensor is capable of compensating for the effect of temperature (programming of a thermal coefficient) on the magnetic system. Such temperature compensation is not perfect, and therefore the only position for which this error has no influence is a position at which induction is zero.

French Patent Application No. 2670286 and European Patent Application No. 0665416, filed in the name of the Applicant, disclose a device in which the angular-position measurement function is achieved by variation of the magnetic induction, but propose a maximum travel of $\pm 90^\circ$ around the zero-gauss position. For sensors of the type presented in the aforesaid two patents, this travel is reduced to $\pm 70^\circ$ around the zero-gauss position in an attempt to obtain excellent linearity (typically $\pm 0.5\%$). Since ETC applications generally necessitate a total travel of close to 90° , two options are possible:

- the use of a symmetric angular range, such as $[-45^\circ; +45^\circ]$, or
- the use of the angular range $[-20^\circ; +70^\circ]$, so as to approach zero gauss.

Thus it is not possible in any of the cases to combine the following three characteristics:

- a zero-gauss starting point (high-stability point),
- a usable angular travel greater than or equal to 90° ,
- excellent linearity ($\pm 0.5\%$) over the chosen angular range.

In fact, if the interval $[-20^\circ; +70^\circ]$, for example, is used, the starting point (-20°) does not operate at zero gauss but exhibits an offset, which is problematic for applications that necessitate a very stable starting point.

In the prior art there is also known US Patent No. 5861745, which describes a contactless detection device comprising a rotor and a stator. In the stator there is disposed a Hall element in an air gap having the form of a slit, and in the interior wall of the rotor there are disposed two annular magnets having mutually opposed magnetic polarities.

Within the scope of use of the angular sensor over the maximum travel (240°) and/or for applications of the ETC type, however, only two structures function theoretically, those illustrated in Figs. 3 and 4, which are composed respectively of an interior stator configuration and an exterior stator configuration. These two devices exhibit the following characteristics: three pieces for the stator and two magnets that are magnetized radially, one (interior radial) over an angular extent of 120° and the other (exterior radial) over an angular extent of 240° .

At present, however, it is not technically feasible to magnetize a magnet correctly over an angular extent of 240° . This degradation of performances leads inevitably to poor linearity and, as it happens, linearity is the primary criterion for sensors of this type.

Finally, there is also known International Patent Application No. WO 0120250, which describes a measuring device for contactless detection of a relative motion, comprising 3 stator poles of approximately 120° by making of a hole in the large stator, with the objective of decreasing the leakage flux when the transition of the magnets is located in the configuration illustrated in particular in Figs. 22, 23, 24a

and 24c of the said application. Thus the device of that patent application does not permit operation in the angular phase $[-120^{\circ}; +120^{\circ}]$, because the presence of the said hole induces an "accident" in the measured induction for the zone close to zero.

The object of the invention is therefore more particularly to remedy the disadvantages of the prior art devices. For this purpose it proposes an angular-position magnetic-sensor device provided with at least one stator and one rotor, the space between the said stator and the said rotor defining over substantially 360° a main air gap in which there move at least two magnetic poles of alternating polarities, the said stator being provided with at least one secondary air gap in which there is placed at least one magnetosensitive element, characterized in that the said stator is composed of two pole shoes having angular widths that are substantially equal to 120° and 240° respectively.

Furthermore, the two magnetic poles will each have an angular width substantially equal to 120° . Advantageously, the aforesaid two magnetic poles will be radially magnetized adjacent magnets.

In one embodiment of the invention, the rotor is situated in the interior of the stator.

In a second embodiment, the rotor is situated on the exterior of the stator.

According to one option presented by the invention, the sides of at least one of the said air gaps could be oriented radially, or in other words "in the form of radial slits", or be oriented in the same direction, or in other words "in the form of straight slits".

Preferably, the sides of the said air gap will be mutually parallel. In the same way, at least one of the said magnetic poles will be advantageously made of a soft ferromagnetic material.

At least one of the magnetic poles could be glued to the rotor or be an integral part of the said rotor.

According to another option, the rotor and stator could be disposed axially, or in other words along the same linear axis. In this case, the said magnetic poles will then be adjacent disc-shaped magnets that are magnetized axially, or in other words along the same linear axis.

The rotor also could comprise at least two axially separate parts, the two parts forming the rotor then being separated by an axially magnetized disc magnet. It will also be possible for the two parts to be separated by an axially magnetized magnet of annular shape.

According to another option presented by the invention, the rotor could comprise at least two transversely separate parts, the two parts forming the rotor then being separated by a transversely magnetized parallelepiped magnet.

In the case in which the rotor is situated on the exterior of the stator, the rotor could comprise at least two parts separated transversely by a transversely magnetized magnet, which magnet can have parallelepiped shape.

By virtue of these features, the invention therefore makes it possible to manufacture, at low cost, an angular-position sensor capable of operating with a linearity of $\pm 0.5\%$ over a travel of 100° starting from the zero-gauss point, and extends the travel from $\pm 90^\circ$ to $\pm 120^\circ$. Thus this sensor exhibits the following characteristics:

- linearity on the order of 1% peak-to-peak,
- delivery of a signal having good linearity over a range of 220° ,
- a stator part reduced to two pieces,
- two magnetic poles that are magnetized preferentially radially over an angular range substantially equal to 120° , easier to use industrially.

By way of non-limitative example, embodiments of the invention will be described hereinafter with reference to the attached drawings, wherein:

- Fig. 1 illustrates a perspective view of an angular-position magnetic-sensor device according to the invention;

- Fig. 2 is an overhead view in horizontal projection of the device illustrated in Fig. 1;

- Figs. 3 and 4 respectively illustrate a perspective view and an overhead view in horizontal projection of another embodiment of the device according to the invention, wherein the rotor is placed in the interior of the stator;

- Figs. 5 and 6 respectively illustrate a perspective view and an overhead view in horizontal projection of another version of the device illustrated in Figs. 3 and 4;

- Figs. 7 and 8 respectively illustrate a perspective view and an overhead view in horizontal projection of another embodiment of the device according to the invention, wherein the rotor is placed on the exterior of the stator;

- Figs. 9 and 10 respectively illustrate a perspective view and an overhead view in horizontal projection of another embodiment of the device according to the invention, wherein the magnetic poles are of the disc type;

- Figs. 11 and 12 respectively illustrate a perspective view and an overhead view in horizontal projection of another embodiment of the device according to the invention, wherein the magnetic poles are independent of the rotor;

- Figs. 13 and 14 respectively illustrate a perspective view and an overhead view in horizontal projection of another embodiment of the device according to the invention, wherein the rotor is axially separated by an axially magnetized disc magnet;

- Fig. 15 illustrates a perspective view of a device according to the invention, wherein the rotor is transversely

separated by a transversely magnetized magnet;

- Figs. 16 and 17 respectively illustrate a perspective view and an overhead view in horizontal projection of another embodiment of the device according to the invention, wherein the rotor is disposed on the exterior of the stator and is separated axially by an axially magnetized annular magnet;

- Fig. 18 illustrates a perspective view of a device according to the invention, wherein the rotor, disposed on the exterior of the stator, is separated transversely by a transversely magnetized magnet.

The angular-position magnetic-sensor device according to the invention comprises, in all examples presented hereinafter as necessary for comprehension and illustration of the different versions of the invention, a stator and a rotor of soft ferromagnetic material as well as two magnetic poles of alternate polarities. A magnetosensitive element, such as a Hall sensor, lodged in a secondary air gap of the stator, measures the induction and makes it possible to obtain the angular position of the rotor relative to the stator.

Furthermore, as is evident in the different figures, regardless of whether the stator is placed on the exterior or in the interior of the rotor, it is always composed of two pole shoes 1, 2 of angular widths substantially equal to 120° and 240° respectively.

In an embodiment illustrated in Figs. 1 and 2, the position-sensor device according to the invention is provided with a stator 1, 2, in the interior of which there is lodged a rotor 3. The space existing between stator 1, 2 and rotor 3 defines main air gap 4, which extends over 360° and in which there move two adjacent magnetic poles 5 and 6 or magnets, which are radially magnetized and have alternate polarities, the said magnets, which are integral with a coupling means, being capable of being glued to the rotor.

Stator 1, 2 is composed of two fixed parts 1 and 2, defining two secondary air gaps 7 and 8, the sides of which, mutually parallel in pairs, are oriented radially. The two secondary air gaps 7 and 8 are substantially perpendicular to main air gap 4, and magnetosensitive element 9, lodged in at least one of the said secondary air gaps 7, 8, measures the variation of induction. This magnetosensitive element 9 generates an electric signal proportional to the induction passing through it.

Figs. 3 and 4 illustrate another version of the angular-position magnetic-sensor device illustrated in Figs. 1 and 2. In fact, in this version, one of the magnets defining one of the two magnetic poles of angular width substantially equal to 120° is replaced by a soft ferromagnetic material. In addition, in the same manner as in the foregoing, rotor 3 is disposed in the interior of stator 1, 2 and the parallel sides of secondary air gaps 7, 8 are oriented radially, in accordance with a known configuration referred to as "in the

form of radial slits".

According to an option presented by the invention, the magnetic poles can be glued to rotor 3 or can be an integral part of rotor 3. In the example illustrated in Fig. 4, magnetic pole 10 formed by the soft ferromagnetic material is therefore an integral part of rotor 3.

In the same manner, an embodiment of the device according to the invention as illustrated in Figs. 5 and 6 could be envisaged, wherein secondary air gaps 7 and 8, whose sides as seen in the foregoing are ideally parallel, are oriented in the same direction, in other words, the said sides respectively extend according to two parallel straight lines A'A and B'B, as are evident in Fig. 6.

Of course, the case in which the sides of the secondary air gaps are not parallel, without significant alternation of the properties of the device according to the invention, also could be imagined. Moreover, for considerations of construction and production, it will be understood that it is easier to provide that the opposite sides of magnetic poles 5, 6 or 6, 10 be parallel.

In a second embodiment of the device according to the invention, the position sensor is provided with a rotor 11, in the interior of which there is lodged a stator 12, 13.

In the same manner as in the foregoing, the space between the said stator 12, 13 and the said rotor 11 defines main air gap 4, which extends over 360° and in which there move two adjacent magnets 5, 6, magnetized radially and of alternate polarity. In equivalent fashion, the said magnets 5 and 6, integral with a coupling means, can be glued to rotor 11 or can be an integral part thereof. The two magnets 5, 6 comprise two magnetic poles of angular width substantially equal to 120° .

Stator 12, 13 in this case is composed of two fixed parts 12 and 13, wherein the space separating them defines a secondary air gap 14 and the two ends of which are substantially perpendicular to main air gap 4. Magnetosensitive element 9, lodged in secondary air gap 14, measures the variation of induction. This magnetosensitive element 9 generates an electric signal proportional to the induction passing through it.

As in the foregoing, it could be imagined that at least one of magnetic poles 5 or 6 of width substantially equal to 120° is replaced by a soft ferromagnetic material.

In an embodiment of the device according to the invention, stator 1, 2 and rotor 15 are disposed axially. The separation space between stator 1, 2 and rotor 15 defines main air gap 4, which extends over 360° and in which there move two magnets 5 and 6, comprising two adjacent magnetic poles, of angular width substantially equal to 120° , disc-shaped, adjacent, magnetized axially, and of alternate polarity, the said magnets 5 and 6, integral with a coupling means, being

capable of being glued to rotor 15.

As in the foregoing, the device according to the invention functions in the same manner in this embodiment. Thus the stator is composed of two fixed parts 1 and 2, defining two secondary air gaps 7 and 8, whose parallel sides are oriented radially. The two secondary air gaps 7 and 8 are substantially perpendicular to main air gap 4, and magnetosensitive element 9, lodged in at least one of the said secondary air gaps 7, 8, measures the variation of induction. This magnetosensitive element 9 generates an electric signal proportional to the induction passing through it.

This version of the device according to the invention could contain, in common with all alternatives of the device according to the invention, at least one of the said magnetic poles 5, 6, that will be composed of a soft ferromagnetic material. In the same way, the opposite and parallel sides of secondary air gaps 7, 8 could be oriented in the same direction.

According to another option presented by the invention and illustrated in Figs. 11 and 12, the angular-position magnetic-sensor device could, in all examples chosen to illustrate the said invention, contain these two magnetic poles 5, 6, independent of both rotor 3 and stator 1, 2. Thus the two said poles 5, 6 neither will be glued to the stator nor will be glued to the rotor, and will be able to move in independent fashion in the interior of the main air gap.

Figs. 13 and 14 illustrate another version of the device of the invention wherein rotor 16 and 17, disposed in the interior of a stator 1, 2, is composed of two parts 16 and 17, to which there are glued magnetic poles 5 and 6 respectively. In addition, the two rotor parts 16, 17 are separated by an axially magnetized disc magnet 18.

Thus, according to the present embodiment, the position sensor is provided with a stator 1, 2, in the interior of which there is lodged a rotor divided into two parts 16 and 17, the two parts 16, 17 being separated axially by an axially magnetized disc magnet 18; in other words, the direction of magnetization thereof is parallel to stacking axis XX' of the two rotor parts 16 and 17 and of the said disc magnet 18. The space existing between stator 1, 2 and rotor 16, 17 defines main air gap 4, which extends over 360° and in which there move two magnetic poles 5, 6, made of soft ferromagnetic material, of alternate polarities, the said magnetic poles 5, 6, which are integral with a coupling means, being capable of being glued to the rotor or of comprising a fraction of each of rotor parts 16 and 17.

As in the other embodiments of the device according to the invention, the stator is composed of two fixed parts 1 and 2, defining two secondary air gaps 7, 8, whose parallel sides are oriented radially. The two secondary air gaps 7, 8 are substantially perpendicular to main air gap 4, and magnetosensitive element 9, lodged in at least one of the said secondary air gaps 7, 8, measures the variation of induction. This magnetosensitive element 9 generates an electric signal proportional to the induction passing through it.

As illustrated in Fig. 15, the two rotor parts 19, 20 could be disposed in the same plane, also containing stator 1, 2. In this version of the device of the invention, the two rotor parts 19, 20 will each comprise a magnetic pole, glued to the said part 19 or 20, for example, and will be separated from one another by a parallelepiped magnet 21, which is magnetized transversely, or in other words along the said plane and perpendicular to the tangents to the circle or portion of a circle formed by stator 1, 2 or the two rotor parts 19, 20.

The other elements of the angular-position magnetic-sensor device according to the invention can be disposed in a manner identical to that in the versions described in the foregoing. Thus, the stator 1, 2 is composed of two fixed parts 1 and 2, defining two secondary air gaps 7, 8, whose parallel sides are oriented radially. The two secondary air gaps 7, 8 are substantially perpendicular to main air gap 4, and magnetosensitive element 9, lodged in at least one of the said secondary air gaps 7, 8, measures the variation of induction. This magnetosensitive element 9 generates an electric signal proportional to the induction passing through it.

Figs. 16 and 17 illustrate a version of the device of the invention wherein stator 22, 23 is placed in the interior of a rotor divided into two parts 24 and 25, these two parts 24, 25 being separated axially by an annular magnet 26 that is magnetized axially, or in other words in the direction parallel to the stack of circles or rings formed by rotor parts 24, 25 and annular magnet 26 separating them. The space between stator 22, 23 and rotor 24, 25 defines main air gap 4, which extends over 360° and in which there move two magnetic poles 5, 6, which are made of soft ferromagnetic material, of alternate polarities.

Magnetic poles 5, 6 could be integral with a means for coupling with rotor parts 24, 25, for example glued to the said parts 24 and 25 or comprise a fraction of the said rotor parts 24, 25. In the case illustrated in Figs. 16 and 17, each rotor part 24 and 25 comprises or supports a magnetic pole 5 or 6.

Stator 22, 23 in this case is composed of two fixed parts 22 and 23, defining a secondary air gap 27, whose two ends are substantially perpendicular to main air gap 4. Magnetosensitive element 9, lodged in secondary air gap 27, measures the variation of induction. As in the foregoing, this magnetosensitive element 9 generates an electric signal proportional to the induction passing through it.

Fig. 18 illustrates, as in the example illustrated in Fig. 15, the two rotor parts 28, 29, disposed in the same plane, also containing stator 30, 31, disposed in the interior of the circle or of the ring formed by the two rotor parts 28, 29. The two rotor parts 28, 29 each comprise a magnetic pole

5, 6, and they will be separated from one another by a magnet 32, which has parallelepiped shape, for example, magnetized transversely, or in other words along the said plane and perpendicular to the tangents to the circle or portion of a circle formed by stator 30, 31 or the two rotor parts 28, 29.

In this example, stator 30, 31 is also composed of two fixed parts 30 and 31, defining a secondary air gap, whose two ends are substantially perpendicular to the main air gap. Magnetosensitive element 9, lodged in the secondary air gap, measures the variation of induction in the same manner as in the other practical examples of the invention.

The invention is described in the foregoing by way of example. It is understood that the person skilled in the art is capable of achieving different versions of the leaktight device according to the invention, especially as regards the form of the stator and/or of the rotor, and of the main and secondary air gaps, without departing from the scope of the patent as a result.

CLAIMS

1. An angular-position magnetic-sensor device provided with at least one stator (1, 2) and one rotor (3), the space between the said stator (1, 2) and the said rotor (3) defining over substantially 360° a main air gap (4) in which there move at least two magnetic poles (5, 6) of alternating polarities, the said stator (1, 2) being provided with at least one secondary air gap (7, 8) in which there is placed at least one magnetosensitive element (9), characterized in that the said stator (1, 2) is composed of two pole shoes (1 and 2) having angular widths that are substantially equal to 120° and 240° respectively, and in that the two magnetic poles (5, 6) each have an angular width substantially equal to 120° .
2. An angular-position magnetic-sensor device according to claim 1, characterized in that the rotor (3) is situated in the interior of the stator (1, 2).
3. An angular-position magnetic-sensor device according to claim 1, characterized in that the rotor (11) is situated on the exterior of the stator (12, 13).
4. An angular-position magnetic-sensor device according to claim 1, characterized in that the aforesaid two magnetic poles (5, 6) are radially magnetized adjacent magnets.

5. An angular-position magnetic-sensor device according to claim 1, characterized in that the sides of the said secondary air gap (7, 8) are oriented radially, or in other words "in the form of radial slits".

6. An angular-position magnetic-sensor device according to claim 1, characterized in that the sides of the said secondary air gap (7, 8) are oriented in the same direction, or in other words "in the form of straight slits".

7. An angular-position magnetic-sensor device according to claim 5 or 6, characterized in that the sides of the said secondary air gap (7, 8) are mutually parallel.

8. An angular-position magnetic-sensor device according to claim 1, characterized in that at least one of the said magnetic poles (5, 6) is made of a soft ferromagnetic material.

9. An angular-position magnetic-sensor device according to claim 1, characterized in that at least one of the magnetic poles (5, 6) is glued to the rotor (3).

10. An angular-position magnetic-sensor device according to claim 1, characterized in that at least one of the magnetic poles (5, 6) is an integral part of the rotor (3).

17. An angular-position magnetic-sensor device according to claim 13, characterized in that the two parts (24, 25) of the rotor are separated by an axially magnetized annular magnet (26).

18. An angular-position magnetic-sensor device according to claim 3, characterized in that the rotor (28, 29) comprises at least two parts (28 and 29) separated transversely by a transversely magnetized magnet (32).

19. An angular-position magnetic-sensor device according to claim 18, characterized in that the magnet (32) has parallelepiped shape.

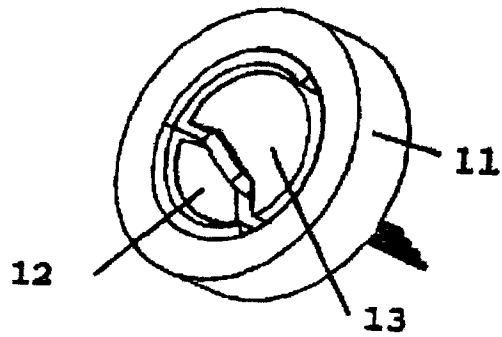
Figure 1

Figure 1 is a perspective view of a circular mechanical assembly. It features a central circular component (3) surrounded by a ring (2). A flange (1) is attached to the top of the ring. A bolt (6) is shown passing through the flange and the ring. A nut (5) is shown on the bottom of the ring. A washer (9) is shown on the left side of the ring. A screw (4) is shown on the right side of the ring.

Figure 2 is a cross-sectional view of a mechanical assembly. It shows a central shaft (3) with a collar (4) and a flange (2). A housing (1) surrounds the shaft, with a seal (7) and a gasket (8) at the interface.

Fig. 1 is a perspective view of a circular device. It features a central hub (3) and a surrounding ring (2). A cable (1) is connected to the ring, and a bundle of wires (9) is connected to the central hub.

Figure 7



Figure

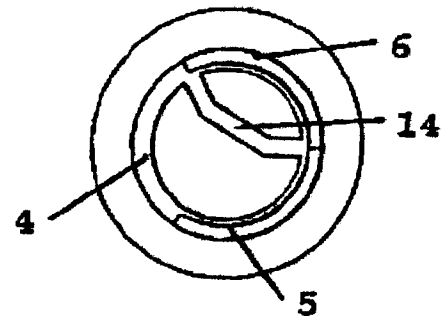


Figure 9

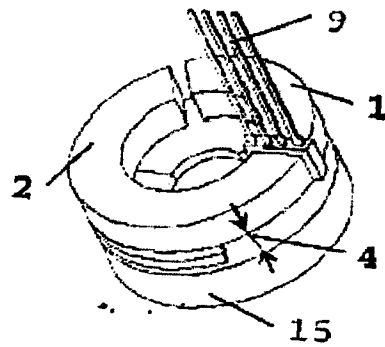


Figure 10

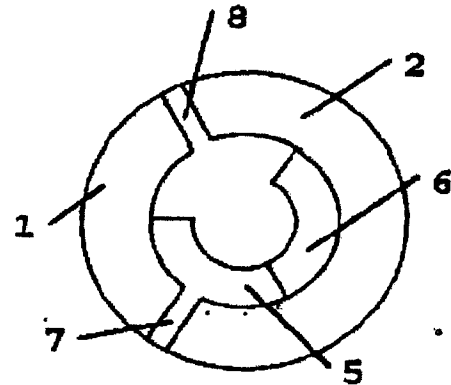


Figure 11

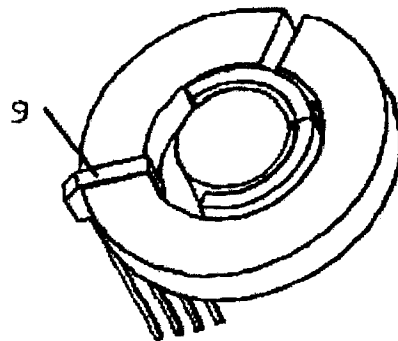


Figure 12

